Course Overview

Welcome to EE445!

- Linear algebra, optimization, & machine learning models motivated by applications in areas including statistics, decision-making and control, communications, signal processing...
- See course website for all logistics, course information, pre-req's, and material
- Books:
 - "Vectors, Matrcies, and Least Squares (VMLS)" by Boyd & Vandenberghe (.pdf is online)
 - 'Optimization Models' by Calafiore & El Ghaoui

(check errata file too)

see other supplementary books
 Strang
 Axler

- Instructors: Maryam Fazel, Lillian Ratliff
- TA: Adhyyan Narang
- Important : HWO assessment HW is assigned (see announcement + website)

[Lecturer: M. Fazel]

EE445 Mod1-Lec1: Linear Algebra I

References:

- [VMLS]: Chapters 1, 2, 3
- Topics: Vectors, Inner product, Linear functions, Regression model, Norm and distance

[Lecturer: M. Fazel]

Vectors: notation

other notation: **x** (boldface)

• a vector is an ordered list of numbers: (-1.2, 0, 3.6), or

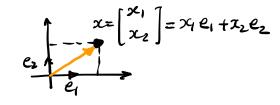
$$x = \begin{bmatrix} -1.2 \\ 0 \\ 3.6 \end{bmatrix} \qquad \qquad \overleftarrow{x}$$

- $x \in \mathbf{R}^n$ means *n*-vector with real entries $y \in \mathcal{C}^n$ (complex numbers), $z \in \mathbb{R}^n_+$ (nonnegative.
- x_i denotes the *i*th entry of x (warning: sometimes x_i refers to *i*th vector in a list of vectors)
- x^T denotes transpose
 1_n or 1 denotes vector of all ones
- i zoro alazzationa) • e_i denotes *i*th coordinate vector (1 in index *i*, zero elsewhere)
- suppose b, c, d are vectors of sizes m, n, p, can stack them into a larger block vector

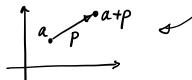
$$a = \begin{bmatrix} b \\ c \\ d \end{bmatrix} \begin{pmatrix} \uparrow m \\ \uparrow n \\ \uparrow p \end{bmatrix} a \in \mathbb{R}^{m + n + p}$$

[Lecturer: M. Fazel]

Examples



• (x_1, x_2) represents a location or a displacement in 2D



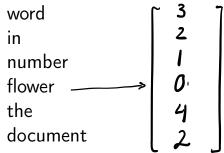
- examples:
- portfolio: entries give shares (or \$ value or fraction) held in each of n assets, with negative meaning short positions get a \$1 loon for period 1- cash flow: x_i is payment in period i to us e.g., [1 1.1 0]
- **–** sampled audio signal: x_i is the acoustic pressure at sample time *i*
- feature vector: x_i is the value of *i*th feature or attribute of an entity
- word count vector

Word count example

• a short document:

"Word count vectors are used in computer based document analysis. Each entry of the word count vector is the number of times the associated dictionary word appears in the document."

• dictionary & word count vector:



Linear combinations

• for vectors
$$\underline{a_1, \ldots, a_n}$$
, scalars $\underline{\beta_1, \ldots, \beta_n}$,
 $\mathbf{g} = \beta_1 a_1 + \ldots + \beta_n a_n$

is a linear combination with coeff's β_1, \ldots, β_n

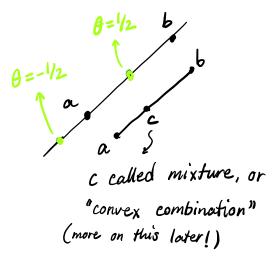
• 2D example:
$$b = 0.75a_1 - a_2$$

ar -ae b a

• line and segment: a, b are n-vectors, $c = (1 - \theta)a + \theta b$

• when $\underline{\theta}$ is any scalar: c on line passing through a, b

• when $0 \le \theta \le 1$: *c* on line segment connecting *a*, *b*



Inner product

• inner product (or dot product) of n-vectors a and b is

$$a^{T}b = \sum_{i=1}^{n} a_{i}b_{i} \qquad (a_{i} - a_{n}) \begin{bmatrix} b_{i} \\ \vdots \\ b_{n} \end{bmatrix} = a_{i}b_{i} + \cdots + a_{n}b_{n}$$

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other notation used: $\langle a,b
angle$, $a\cdot b$, $\langle a|b
angle$

$$e_{X:} \quad [-1 \quad 2 \quad 2] \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix} = (-1)(1) + (2)(0) + (2)(-3) = -7$$

Properties of inner product

a, belR", selR

- $a^Tb = b^Ta$
- $(\gamma a)^T b = \gamma(a^T b)$
- $(a+b)^T c = a^T c + b^T c$

examples:

•
$$\underbrace{e_i^T a}_{1^T a} = \underbrace{a_i}_{i=1}^n (e_i: i \text{th coordinate vector})$$

• $\underbrace{\mathbf{1}^T a}_{a^T a} = \underbrace{\sum_{i=1}^n a_i}_{i=1}^n (\mathbf{1}: \text{ vector of all ones})$
• $\underline{a^T a} = \underbrace{\sum_{i=1}^n a_i^2}_{i=1} = I a I^2$

Examples

- w is weight vector, f is feature vector; $w^T f$ is score e.g. credit score
- p is vector of asset prices, s gives portfolio holdings (in shares); $p^T s$ is total portfolio value
- c is cash flow, d is discount vector (with interest rate r):

$$d = (1, 1/(1+r), \dots, \frac{1}{2}/(1+r)^{n-1})$$

 $\ensuremath{\textit{MPV}}\xspace^T c$ is net present-value of cash flow

Linear functions

- $f: \mathbb{R}^n \to \mathbb{R}$ means f is a function mapping n-vectors to scalars (multivariate function of n variables)
- note: we'll also see $\mathbf{R}^n
 ightarrow \mathbf{R}^m$ linear maps soon
- f satisfies superposition if $f(\alpha x + \beta y) = \alpha f(x) + \beta f(y)$ holds for all scalars α, β and all $x, y \in \mathbf{R}^n$
- then *f* is called a *linear* function
- example: the 'inner product function' is linear:

f(hn camp of x.u)=

LHS:
$$a^{T}(\alpha x + \beta y) = \alpha a^{T}x + \beta a^{T}y$$
 some

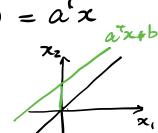
RHS:
$$\alpha(\alpha^T z) + \beta(\alpha^T y)$$

... and all linear functions are inner products

- suppose $f: \mathbf{R}^n \to \mathbf{R}$ is linear, then it can be expressed as $f(x) = a^T x$ for some a
- specifically: $a_i = f(e_i)$
- follows from:

• 'affine' function: a linear function plus a constant, general form:

$$f(x) = a^T x + \underline{b}$$



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• sometimes (sloppily) we refer to this as linear also

[Lecturer: M. Fazel]

Regression model

• *regression model* is (affine function of *x*):

$$\hat{y} = x^T \beta + v$$

- x is a feature vector, element x_i called regressors
- β is the *weight vector*, scalar v is the *offset*
- scalar \hat{y} is the *prediction* (of some actual outcome y)

Example: house prices

- y is selling price of house (in \$1000)
- regressor is x = (house area in 1000 sqft, # bedrooms)
- weight vector and offset are: $\beta = (148.73, \bigcirc 18.85)$, v =

, interpret as
$$= 54.4$$
 'land value'

- will later see how to guess β and v from sales data
- data: G in module 2

house	x_1 (area)	x_2 (bed)	y (price)	\hat{y} (prediction)
1	0.846	1	115.00	161.37
2	1.324	2	234.50	213.61
3	1.150	3	198.00	168.88
4	3.0337	4	528.00	430.67
5	3.984	5	572.50	552.66

Example: house prices

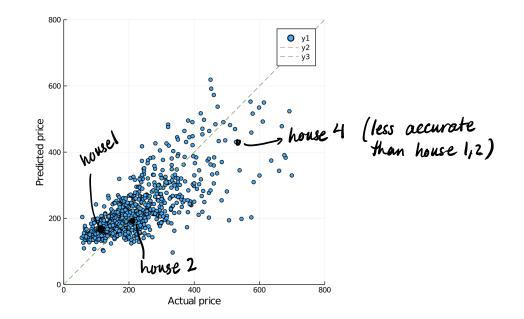


Figure: Scatter plot of actual and predicted sale prices for 774 houses sold in Sacramento in a 5-day period

[Lecturer: M. Fazel]

Norm and distance

XEIRⁿ

• Euclidean norm (2-norm) is $||x|| = \sqrt{\sum_{i=1}^{n} x_i^2}$



- properties:
 - homogeneity: $\|\alpha x\| = |\alpha| \|x\|$
 - ► triangle inequality: $\|x+y\| \leq \|x\| + \|y\|$
 - ▶ nonnegativity: ||𝒴||≥₀
 - ► definiteness: ||x||=0 only if x=0

Norm and distance

• norm of block vectors:
$$\left\| \begin{bmatrix} a \\ b \\ c \end{bmatrix} \right\|^{2} = [a \ b \ c] \begin{bmatrix} a \\ b \\ c \end{bmatrix} = a^{T}a + b^{T}b + c^{T}c$$

$$||(a,b,c)||^2 = a^T a + b^T b + c^T c = ||a||^2 + ||b||^2 + ||c||^2$$

- (Euclidean) distance between vectors a, b is: $\underline{\operatorname{dist}(a, b)} = ||a b||$
- triangle inequality: $||a c|| \le ||a b|| + ||b c||$

$$||a-c|| = ||a-b+b-c|| \le ||a-b|| + ||b-c||$$

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Chebyshev inequality

Simple but useful ineq. on relation between vector norm & vector entries :

$$\begin{array}{l|l} \textbf{x} \in \mathbb{R}^{n} \\ \hline \text{suppose that } k \text{ of the numbers } |x_{1}|, \ldots, |x_{n}| \text{ are } \geq a \\ \hline \text{suppose that } k \text{ of the numbers } x_{1}^{2}, \ldots, x_{n}^{2} \text{ are } \geq a^{2} \\ \hline \text{so } \|x\|^{2} = \sum_{i} x_{i}^{2} \geq ka^{2}, \text{ and we have } k \leq \|x\|^{2}/a_{A}^{2} \\ \hline \text{number of } x_{i} \text{ with } |x_{i}| \geq a \text{ is no more than } \|x\|^{2}/a^{2} \\ \hline \text{this is the Chebyshev inequality} \\ \hline \text{define root-mean-square value: } rms(x) = \sqrt{\frac{x^{2}+\dots+2x_{n}^{2}}{n}} = \frac{\|x\|}{\sqrt{n}} \\ \hline \text{Chebyshev ineq. in terms of rms value:} \\ \hline \text{fraction of entries } w/|xi| \geq a \left(inc_{Y}, \frac{k}{n}\right) \text{ is no more than } \frac{\|x\|^{2}}{na^{2}} = \left(\frac{rms(x)}{a}\right)^{2} \\ \hline \text{[Lecturer: M. Fazel]} \\ \hline \end{array}$$